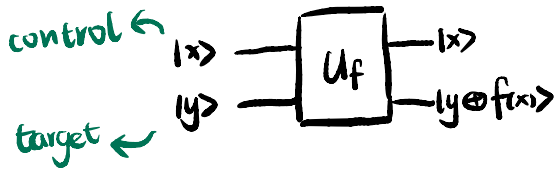


# Deutsch-Josza Algorithm

## I. The Quantum Oracle



Notation:  $\oplus$  is addition modulo 2.  
 $a \oplus b := a + b \pmod{2}$

$a \oplus b$		$b$	
		0	1
$a$	0	0	1
	1	1	0

$$U_f(|x\rangle|y\rangle) = |x\rangle|y \oplus f(x)\rangle$$

### Cheat Sheet

- $x \oplus 0 = x$
- $x \oplus 1 = !x$ , we say  $x$  is flipped

$x=0$  or  $x=1$

1.  $f$  is a binary function  
 $f: \mathbb{Z}_2 \rightarrow \mathbb{Z}_2$

2. There are four possible functions

$x$	$f_1(x)$	$f_2(x)$	$f_3(x)$	$f_4(x)$
0	0	1	0	1
1	0	0	1	1

3.  $f$  is constant if  $f(0) = f(1)$   
 $f_1(x)$  &  $f_4(x)$

4.  $f$  is balanced if  $f(0) \oplus f(1) = 1$   
 $f_2(x)$  &  $f_3(x)$

## II. Task

Determine if  $f$  is constant or balanced using as few queries to the Quantum Oracle shown above as possible.

## III. When $|x\rangle, |y\rangle$ are Computational Basis

Case 1:  $f=f_1$

- $|0\rangle|0\rangle$
- $|1\rangle|0\rangle$
- $|0\rangle|1\rangle$
- $|1\rangle|1\rangle$

Case 2:  $f=f_2$

- $|0\rangle|1\rangle$
- $|1\rangle|0\rangle$
- $|0\rangle|0\rangle$
- $|1\rangle|1\rangle$

Case 3:  $f=f_3$

- $|0\rangle|0\rangle$
- $|1\rangle|1\rangle$
- $|0\rangle|1\rangle$
- $|1\rangle|0\rangle$

Case 4:  $f=f_4$

- $|0\rangle|1\rangle$
- $|1\rangle|1\rangle$
- $|0\rangle|0\rangle$
- $|1\rangle|0\rangle$

- $U_f(|0\rangle|0\rangle) = |0\rangle|f(0)\rangle$
- $U_f(|1\rangle|0\rangle) = |1\rangle|f(1)\rangle$
- $U_f(|0\rangle|1\rangle) = |0\rangle|!f(0)\rangle$
- $U_f(|1\rangle|1\rangle) = |1\rangle|!f(1)\rangle$

By querying the Quantum Oracle twice, we can determine if  $f$  is constant or balanced. Could we do better?

## IV. Navigation

1. When **only** control is in a superposition state, e.g.,  $|x\rangle = |+\rangle = \frac{|0\rangle + |1\rangle}{\sqrt{2}}$

$U_f( +\rangle 0\rangle) = U_f\left(\frac{ 0\rangle+ 1\rangle}{\sqrt{2}}\otimes 0\rangle\right)$ $= U_f\left(\frac{ 00\rangle+ 10\rangle}{\sqrt{2}}\right)$ $= \frac{1}{\sqrt{2}}[U_f( 00\rangle) + U_f( 10\rangle)]$ $= \frac{1}{\sqrt{2}}[ 0\rangle f(0)\rangle +  1\rangle f(0)\rangle]$	$U_f( +\rangle 1\rangle) = U_f\left(\frac{ 0\rangle+ 1\rangle}{\sqrt{2}}\otimes 1\rangle\right)$ $= U_f\left(\frac{ 01\rangle+ 11\rangle}{\sqrt{2}}\right)$ $= \frac{1}{\sqrt{2}}[U_f( 01\rangle) + U_f( 11\rangle)]$ $= \frac{1}{\sqrt{2}}[ 0\rangle f(1)\rangle +  1\rangle f(1)\rangle]$	$U_f( -\rangle 0\rangle) = U_f\left(\frac{ 0\rangle- 1\rangle}{\sqrt{2}}\otimes 0\rangle\right)$ $= U_f\left(\frac{ 00\rangle- 10\rangle}{\sqrt{2}}\right)$ $= \frac{1}{\sqrt{2}}[U_f( 00\rangle) - U_f( 10\rangle)]$ $= \frac{1}{\sqrt{2}}[ 0\rangle f(0)\rangle -  1\rangle f(0)\rangle]$	$U_f( -\rangle 1\rangle) = U_f\left(\frac{ 0\rangle- 1\rangle}{\sqrt{2}}\otimes 1\rangle\right)$ $= U_f\left(\frac{ 01\rangle- 11\rangle}{\sqrt{2}}\right)$ $= \frac{1}{\sqrt{2}}[U_f( 01\rangle) - U_f( 11\rangle)]$ $= \frac{1}{\sqrt{2}}[ 0\rangle f(1)\rangle -  1\rangle f(1)\rangle]$
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Reasoning analogously as before, we can analyze each output state when  $f \in \{f_1, f_2, f_3, f_4\}$ .

Let's use  $U_f(|+\rangle|0\rangle) = \frac{1}{\sqrt{2}}[|0\rangle|f(0)\rangle + |1\rangle|f(0)\rangle]$  as an example.

Case 1:  $f=f_1$

$$U_f(|+\rangle|0\rangle) = \frac{1}{\sqrt{2}}(|00\rangle + |10\rangle) = |+\rangle|0\rangle = |\Psi_1\rangle$$

Case 2:  $f=f_2$

$$U_f(|+\rangle|0\rangle) = \frac{1}{\sqrt{2}}(|01\rangle + |10\rangle) = |\Psi_2\rangle \text{ entangled!}$$

Case 3:  $f=f_3$

$$U_f(|+\rangle|0\rangle) = \frac{1}{\sqrt{2}}(|00\rangle + |11\rangle) = |\Psi_3\rangle \text{ entangled!}$$

Case 4:  $f=f_4$

$$U_f(|+\rangle|0\rangle) = \frac{1}{\sqrt{2}}(|01\rangle + |11\rangle) = |+\rangle|1\rangle = |\Psi_4\rangle$$

However  $\langle \Psi_1 | \Psi_2 \rangle = \frac{1}{2}$ , this means  $|\Psi_1\rangle$  and  $|\Psi_2\rangle$  are indistinguishable. Or in other words, there is no measurement that we could make to distinguish  $|\Psi_1\rangle$  from  $|\Psi_2\rangle$ . Reasoning analogously,  $\{|\Psi_1\rangle, |\Psi_2\rangle, |\Psi_3\rangle, |\Psi_4\rangle\}$  are pair-wise indistinguishable. Hence we could not tell from the measurements if we have a constant function or a balanced function.

2. When only target is in a superposition state, e.g.,  $|y\rangle = |+\rangle = \frac{|0\rangle + |1\rangle}{\sqrt{2}}$

$$U_f(|0\rangle|+\rangle) = U_f\left(|0\rangle \otimes \frac{|0\rangle+|1\rangle}{\sqrt{2}}\right)$$

$$= U_f\left(\frac{|00\rangle+|01\rangle}{\sqrt{2}}\right)$$

$$= \frac{1}{\sqrt{2}}[U_f(|00\rangle) + U_f(|01\rangle)]$$

$$= \frac{1}{\sqrt{2}}[|0\rangle|f(0)\rangle + |0\rangle|f(1)\rangle]$$

$$U_f(|1\rangle|+\rangle) = U_f\left(|1\rangle \otimes \frac{|0\rangle+|1\rangle}{\sqrt{2}}\right)$$

$$= U_f\left(\frac{|10\rangle+|11\rangle}{\sqrt{2}}\right)$$

$$= \frac{1}{\sqrt{2}}[U_f(|10\rangle) + U_f(|11\rangle)]$$

$$= \frac{1}{\sqrt{2}}[|1\rangle|f(0)\rangle + |1\rangle|f(1)\rangle]$$

$$U_f(|0\rangle|-\rangle) = U_f\left(|0\rangle \otimes \frac{|0\rangle-|1\rangle}{\sqrt{2}}\right)$$

$$= U_f\left(\frac{|00\rangle-|01\rangle}{\sqrt{2}}\right)$$

$$= \frac{1}{\sqrt{2}}[U_f(|00\rangle) - U_f(|01\rangle)]$$

$$= \frac{1}{\sqrt{2}}[|0\rangle|f(0)\rangle - |0\rangle|f(1)\rangle]$$

$$U_f(|1\rangle|-\rangle) = U_f\left(|1\rangle \otimes \frac{|0\rangle-|1\rangle}{\sqrt{2}}\right)$$

$$= U_f\left(\frac{|10\rangle-|11\rangle}{\sqrt{2}}\right)$$

$$= \frac{1}{\sqrt{2}}[U_f(|10\rangle) - U_f(|11\rangle)]$$

$$= \frac{1}{\sqrt{2}}[|1\rangle|f(0)\rangle - |1\rangle|f(1)\rangle]$$

Reasoning analogously as before, we can analyze each output state when  $f \in \{f_1, f_2, f_3, f_4\}$ .

Let's use  $U_f(|0\rangle|+\rangle) = \frac{1}{\sqrt{2}}[|0\rangle|f(0)\rangle + |0\rangle|f(1)\rangle]$  &  $U_f(|1\rangle|-\rangle) = \frac{1}{\sqrt{2}}[|1\rangle|f(0)\rangle - |1\rangle|f(1)\rangle]$  as examples.

Case 1:  $f=f_1$

$$U_f(|0\rangle|+\rangle) = \frac{1}{\sqrt{2}}[|0\rangle|0\rangle + |0\rangle|0\rangle] = |0\rangle|+\rangle$$

$$U_f(|1\rangle|-\rangle) = \frac{1}{\sqrt{2}}[|1\rangle|0\rangle - |1\rangle|0\rangle] = |1\rangle|-\rangle$$

Case 2:  $f=f_2$

$$U_f(|0\rangle|+\rangle) = \frac{1}{\sqrt{2}}[|0\rangle|1\rangle - |0\rangle|0\rangle] = -|0\rangle|+\rangle$$

$$U_f(|1\rangle|-\rangle) = \frac{1}{\sqrt{2}}[|1\rangle|0\rangle - |1\rangle|1\rangle] = |1\rangle|-\rangle$$

Case 3:  $f=f_3$

$$U_f(|0\rangle|+\rangle) = \frac{1}{\sqrt{2}}[|0\rangle|0\rangle + |0\rangle|1\rangle] = |0\rangle|+\rangle$$

$$U_f(|1\rangle|-\rangle) = \frac{1}{\sqrt{2}}[|1\rangle|1\rangle - |1\rangle|0\rangle] = -|1\rangle|-\rangle$$

Case 4:  $f=f_4$

$$U_f(|0\rangle|+\rangle) = \frac{1}{\sqrt{2}}[|0\rangle|1\rangle - |0\rangle|0\rangle] = -|0\rangle|+\rangle$$

$$U_f(|1\rangle|-\rangle) = \frac{1}{\sqrt{2}}[|1\rangle|1\rangle - |1\rangle|0\rangle] = -|1\rangle|-\rangle$$

$$U_f(|x\rangle|-\rangle) = U_f\left(\frac{|x\rangle|0\rangle - |x\rangle|1\rangle}{\sqrt{2}}\right)$$

$$= \frac{1}{\sqrt{2}}[U_f(|x\rangle|0\rangle) - U_f(|x\rangle|1\rangle)]$$

$$= \frac{1}{\sqrt{2}}[|x\rangle|f(x)\rangle - |x\rangle|f(x)\rangle]$$

$$= (-1)^{f(x)} |x\rangle|-\rangle \quad (*)$$

3. When both control and target are in superpositions.

Let's consider  $|x\rangle = |+\rangle$  and  $|y\rangle = |-\rangle$ :

$$\begin{aligned}
 U_f(|+\rangle|-\rangle) &= U_f\left(\frac{|0\rangle+|1\rangle}{\sqrt{2}}\right)|-\rangle = \frac{1}{\sqrt{2}} [U_f(|0\rangle|-\rangle) + U_f(|1\rangle|-\rangle)] \\
 &\stackrel{(*)}{=} \frac{1}{\sqrt{2}} [(-1)^{f(0)}|0\rangle|-\rangle + (-1)^{f(1)}|1\rangle|-\rangle] \\
 &= \frac{(-1)^{f(0)}}{\sqrt{2}} [ |0\rangle|-\rangle + (-1)^{f(1)-f(0)}|1\rangle|-\rangle ] \quad (**).
 \end{aligned}$$

Case 1 or Case 4: When  $f=f_1$  or  $f=f_4$ , i.e., when  $f$  is constant.

$$f(0) - f(1) = 0$$

$$\text{Hence } (***) = \frac{(-1)^{f(0)}}{\sqrt{2}} (|0\rangle|-\rangle + |1\rangle|-\rangle) = (-1)^{f(0)} |+\rangle|-\rangle$$

→ global phase could be omitted.

Case 2 or Case 3: When  $f=f_2$  or  $f=f_3$  i.e., when  $f$  is balanced

$$f(0) - f(1) = 1 \text{ or } -1$$

$$\text{Hence } (***) = \frac{(-1)^{f(0)}}{\sqrt{2}} (|0\rangle|-\rangle - |1\rangle|-\rangle) = (-1)^{f(0)} |-\rangle|-\rangle$$

→ global phase could be omitted.

Note:  $(-1)^1 = (-1)^{-1} = -1$

Hence, measuring the control qubit in the X basis tells us whether the function is constant or balanced in just **ONE** query. A visualization is shown below.

